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General Equilibrium Macroeconomic Models and Superior Information

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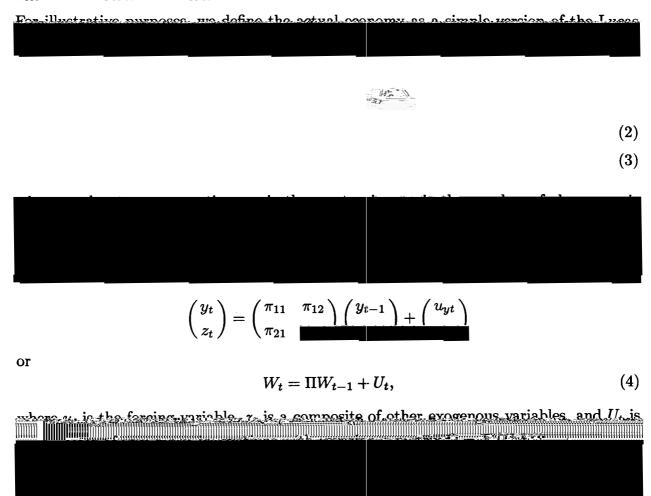
Michel Normandin Department of Economics



1. Introduction



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$$X_t = \Gamma X_{t-1} + V_t, \tag{7}$$

where $X_t = y_t \quad p_t)' = \Upsilon W_t, \ \Gamma = \Upsilon \Pi \Upsilon^{-1}, \ V_t = \Upsilon U_t, \ \text{and} \ \Upsilon = (e_1' \quad \Theta')'$

3. The Artificial Economy

As in most RBC studies, this law of motion involves only the forcing variable:

$$y_{dt} = \gamma y_{dt-1} + v_{yt}.\tag{8}$$

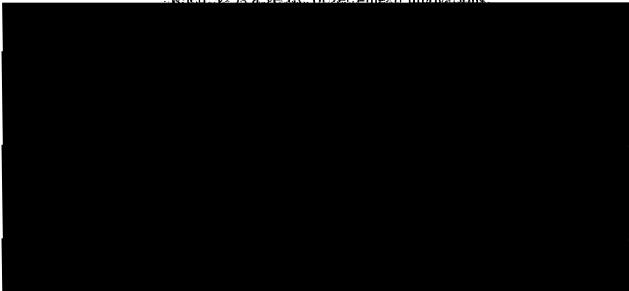
1255 rom estimates of (s) to obtain we construct and expectations a

$$p_{st} = \left(\begin{array}{c} \\ \end{array} \right) y_{dt} = \lambda y_{dt}, \tag{9}$$

$$\underline{X} = \prod_{n=1}^{\Gamma} \underbrace{X}_{n+1} + \underbrace{V}_{n+1}$$
(10)

3.2. The Augmented Law of Motion

$$X_{dt} = \Gamma X_{dt-1} + V_t,$$



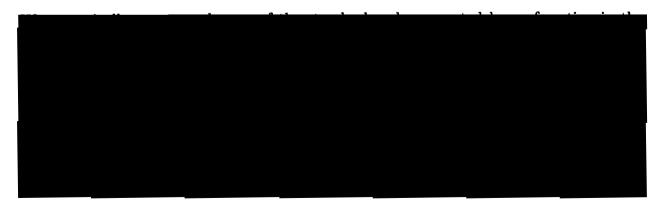
$$p_{at} = e_1 \beta \Gamma \left(I - \beta \Gamma \right)^{-1} X_{dt} = \Lambda X_{dt} = \lambda_1 y_{dt} + \lambda_2 p_{dt},$$

enkoran is the estimated price corrige reported under the automated law of motion - The

$$X_{at} = \Gamma_a X_{at-1} + V_{at},$$

 $= \bigcup_{a} \bigcup_$

3.3. A Numerical Comparison



 $\chi^2(1)$ -distributed test that a generated statistic is identical to the true statistic. Note that

4. Conclusion

The standard procedure to evaluate general equilibrium macroeconomic models is a joint



References

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King, R.G., C.I. Plosser, and S. Rebelo 1988, Production, Growth and Business Cucles

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Panel A: No Superior Information

		$\pi_{12}=0.0$				
$\pi_{11} = \pi_{22}$	Statistic	True	Standard	Augmented		
	p(n. n)	<u>_</u> ^.49	0.37 (0.94) -0.49 (1.00) -1.00 (1.00)	0.37 (0.94) -0.49 (1.00) -1.00 (1.00)		
	$\sigma_p \ ho(p_t,p_{t-1}) \ ho(p_t,y_t)$	1.03 0.51 1.00	$1.06 (0.92) \\ 0.51 (1.00) \\ 1.00 (1.00)$	1.06 (0.92)		

Panel B: Superior Information

		$\pi_{12} = -0.5$			$\pi_{12}=0.5$		
$\pi_{11} = \pi_{22}$	Statistic	Tree	Standard	Augmented	True	Standard	Augmented
	σ_p	0.59			0.57 -0.69 -0.90	0.49 (0.20) -0.56 (0.02) -1.00 (0.00)	0.54 (0.70) -0.69 (1.00) -0.90 (1.00)
	$\sigma_p \ ho(p_t,p_{t-1}) \ ho(p_t,y_t)$	0.49 0.04 0.00	0.06 (0.00) -0.06 (0.16) -1.00 (0.32)	0.51 (0.80) -0.05 (0.36)	0.53 -0.03 -0.06	0.02 (0.00) -0.01 (0.86) -1.00 (0.35)	0.57 (0.71) 0.02 (0.61) 0.03 (0.59)
	$\sigma_p \ ho(p_t,p_{t-1}) \ ho(p_t,y_t)$	2.77	$\begin{array}{c} 2.26 \ (0.41) \\ 0.58 \ (0.94) \\ 1.00 \ (0.90) \end{array}$	$\begin{array}{c} 2.53 \ (0.74) \\ 0.62 \ (0.52) \\ 0.82 \ (0.22) \end{array}$	2.89 0.64	1. 76 (0.07)	